




Variable speed starter, Rated operational voltage 400 V AC, 3-phase, I_e 11.3 A, 5.5 kW, 7.5 HP, Radio interference suppression filter

Part no. DE1-34011FN-N20N
Catalog No. 174339
Alternate Catalog No. DE1-34011FN-N20N
EL-Nummer (Norway) 4110103

Delivery program

| | | | |
|------------------------------------|-----------------|----|---|
| Product range | | | Variable speed starter |
| Part group reference (e.g. DIL) | | | DE1 |
| | | |  |
| Rated operational voltage | U _e | | 400 V AC, 3-phase 480 V AC, 3-phase |
| Output voltage with V _e | U ₂ | | 400 V AC, 3-phase 480 V AC, 3-phase |
| Mains voltage (50/60Hz) | U _{LN} | V | 380 (-10%) - 480 (+10%) |
| Rated operational current | | | |
| At 150% overload | I _e | A | 11.3 |
| Note | | | Rated operational current at an operating frequency of 16 kHz and an ambient air temperature of +50 °C |
| Assigned motor rating | | | |
| Note | | | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 400 V, 50 Hz |
| 150 % Overload | P | kW | 5.5 |
| 150 % Overload | I _M | A | 11.3 |
| Note | | | at 440 - 480 V, 60 Hz |
| 150 % Overload | P | HP | 7.5 |
| 150 % Overload | I _M | A | 11 |
| Degree of Protection | | | IP20/NEMA0 |
| Interface/field bus (built-in) | | | OP-Bus (RS485)/Modbus RTU |
| Fitted with | | | Radio interference suppression filter |
| Parameterization | | | Keypad Fieldbus drivesConnect drivesConnect mobile (App) |
| Frame size | | | FS2 |
| Connection to SmartWire-DT | | | yes in conjunction with DX-NET-SWD3 SmartWire DT module |

Technical data

General

| | | | |
|------------------------------------|----------------|----|---|
| Standards | | | Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1 |
| Certifications | | | CE, UL, cUL, RCM |
| Production quality | | | RoHS, ISO 9001 |
| Climatic proofing | ρ _w | % | < 95%, average relative humidity (RH), non-condensing, non-corrosive |
| Ambient temperature | | | |
| Operating ambient temperature min. | | °C | -10 |
| Operating ambient temperature max. | | °C | +60 |
| | | | Derating between 50 °C and 60 °C: None if f _{PWM} ≤ 16 kHz |

| | | | |
|-----------------------------------|---|----|---|
| | | | None if $I_e \leq 10.6$ A and $f_{PWM} \leq 20$ kHz None up to a max. of 57 °C |
| | | | operation (150 % overload); max. +60 °C |
| Storage | θ | °C | -40 - +70 |
| Radio interference level | | | |
| Radio interference class (EMC) | | | C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |
| Environment (EMC) | | | 1st and 2nd environments as per EN 61800-3 |
| maximum motor cable length | l | m | C2 ≤ 10 m C3 ≤ 25 m |
| Mechanical shock resistance | | g | 15 (11 m/s, EN 60068-2-27) |
| Vibration | | | EN 61800-5-1 |
| Altitude | | m | 0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 2000 m |
| Degree of Protection | | | IP20/NEMA0 |
| Protection against direct contact | | | BGV A3 (VBG4, finger- and back-of-hand proof) |

Main circuit

| | | | |
|--|------------|-----|--|
| Supply | | | |
| Rated operational voltage | U_e | | 400 V AC, 3-phase 480 V AC, 3-phase |
| Mains voltage (50/60Hz) | U_{LN} | V | 380 (-10%) - 480 (+10%) |
| Input current (150% overload) | I_{LN} | A | 12 |
| Supply frequency | f_{LN} | Hz | 50/60 |
| Frequency range | f_{LN} | Hz | 45–66 (± 0%) |
| Mains switch-on frequency | | | Maximum of one time every 30 seconds |
| Power section | | | |
| Overload current (150% overload) | I_L | A | 16.95 |
| max. starting current (High Overload) | I_H | % | 200 |
| Note about max. starting current | | | for 1.875 seconds every 600 seconds |
| Output voltage with V_e | U_2 | | 400 V AC, 3-phase 480 V AC, 3-phase |
| Output Frequency | f_2 | Hz | 0 - 50/60 (max. 300) |
| Switching frequency | f_{PWM} | kHz | 16 adjustable 4 - 32 (audible) |
| Operation Mode | | | U/f control Speed control with slip compensation |
| Frequency resolution (setpoint value) | Δf | Hz | 0.025 |
| Rated operational current | | | |
| At 150% overload | I_e | A | 11.3 |
| Note | | | Rated operational current at an operating frequency of 16 kHz and an ambient air temperature of +50 °C |
| Heat dissipation at current/speed [%] | | | |
| Current = 100% | | | |
| Speed = 0 % | P_V | W | 110 |
| Speed = 50 % | P_V | W | 121 |
| Speed = 90 % | P_V | W | 132 |
| Current = 50 % | | | |
| Speed = 0 % | P_V | W | 72 |
| Speed = 50 % | P_V | W | 85 |
| Speed = 90 % | P_V | W | 88 |
| Current = 50 % | | | |
| Speed = 0 % | P_V | W | 58 |
| Speed = 50 % | P_V | W | 64 |
| Maximum leakage current to ground (PE) without motor | I_{PE} | mA | < 3.5 AC, < 10 DC |
| Fitted with | | | Radio interference suppression filter |
| Frame size | | | FS2 |
| Motor feeder | | | |

| | | | |
|---|---|-----|---|
| Note | | | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm^{-1} at 50 Hz or 1800 min^{-1} at 60 Hz |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 400 V, 50 Hz |
| 150 % Overload | P | kW | 5.5 |
| Note | | | at 440 - 480 V, 60 Hz |
| 150 % Overload | P | HP | 7.5 |
| Apparent power | | | |
| Apparent power at rated operation 400 V | S | kVA | 7.62 |
| Apparent power at rated operation 480 V | S | kVA | 9.15 |
| Braking function | | | |
| Standard braking torque | | | max. 30 % M_N |
| DC braking torque | | | adjustable to 100 % |

Control section

| | | | |
|--------------------------------|-------|---|--|
| Reference voltage | U_s | V | 10 V DC (max. 0.2 mA) |
| Analog inputs | | | 1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA |
| Digital inputs | | | 4, parameterizable, 10 - 30 V DC |
| Relay outputs | | | 1, N/O contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) |
| Interface/field bus (built-in) | | | OP-Bus (RS485)/Modbus RTU |

Assigned switching and protective elements

| | | | |
|---|--|---|--|
| Power Wiring | | | |
| Safety device (fuse or miniature circuit-breaker) | | | |
| IEC (Type B, gG), 150 % | | | FAZ-B16/3 |
| UL (Class CC or J) | | A | 15 |
| Mains contactor | | | |
| 150 % overload (CT/ I_H , at 50 °C) | | | DILM7-... |
| Main choke | | | |
| 150 % overload (CT/ I_H , at 50 °C) | | | DX-LN3-016 |
| Radio interference suppression filter (external, 150 %) | | | DX-EMC34-016 |
| Radio interference suppression filter, low leakage currents (external, 150 %) | | | DX-EMC34-016-L |
| Note regarding radio interference suppression filter | | | Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments |
| Motor feeder | | | |
| motor choke | | | |
| 150 % overload (CT/ I_H , at 50 °C) | | | DX-LM3-011 |

Design verification as per IEC/EN 61439

| | | | |
|--|------------|----|--|
| Technical data for design verification | | | |
| Rated operational current for specified heat dissipation | I_n | A | 11.3 |
| Heat dissipation per pole, current-dependent | P_{vid} | W | 0 |
| Equipment heat dissipation, current-dependent | P_{vid} | W | 159 |
| Static heat dissipation, non-current-dependent | P_{vs} | W | 0 |
| Heat dissipation capacity | P_{diss} | W | 0 |
| Operating ambient temperature min. | | °C | -10 |
| Operating ambient temperature max. | | °C | 60 |
| IEC/EN 61439 design verification | | | |
| 10.2 Strength of materials and parts | | | |
| 10.2.2 Corrosion resistance | | | |
| | | | Meets the product standard's requirements. |
| 10.2.3.1 Verification of thermal stability of enclosures | | | |
| | | | Meets the product standard's requirements. |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat | | | |
| | | | Meets the product standard's requirements. |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects | | | |
| | | | Meets the product standard's requirements. |
| 10.2.4 Resistance to ultra-violet (UV) radiation | | | |
| | | | Meets the product standard's requirements. |
| 10.2.5 Lifting | | | |
| | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 Mechanical impact | | | |
| | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 Inscriptions | | | |
| | | | Meets the product standard's requirements. |

| | | |
|--|--|--|
| 10.3 Degree of protection of ASSEMBLIES | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 Clearances and creepage distances | | Meets the product standard's requirements. |
| 10.5 Protection against electric shock | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.6 Incorporation of switching devices and components | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 Internal electrical circuits and connections | | Is the panel builder's responsibility. |
| 10.8 Connections for external conductors | | Is the panel builder's responsibility. |
| 10.9 Insulation properties | | |
| 10.9.2 Power-frequency electric strength | | Is the panel builder's responsibility. |
| 10.9.3 Impulse withstand voltage | | Is the panel builder's responsibility. |
| 10.9.4 Testing of enclosures made of insulating material | | Is the panel builder's responsibility. |
| 10.10 Temperature rise | | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating | | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.12 Electromagnetic compatibility | | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.13 Mechanical function | | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed. |

Technical data ETIM 8.0

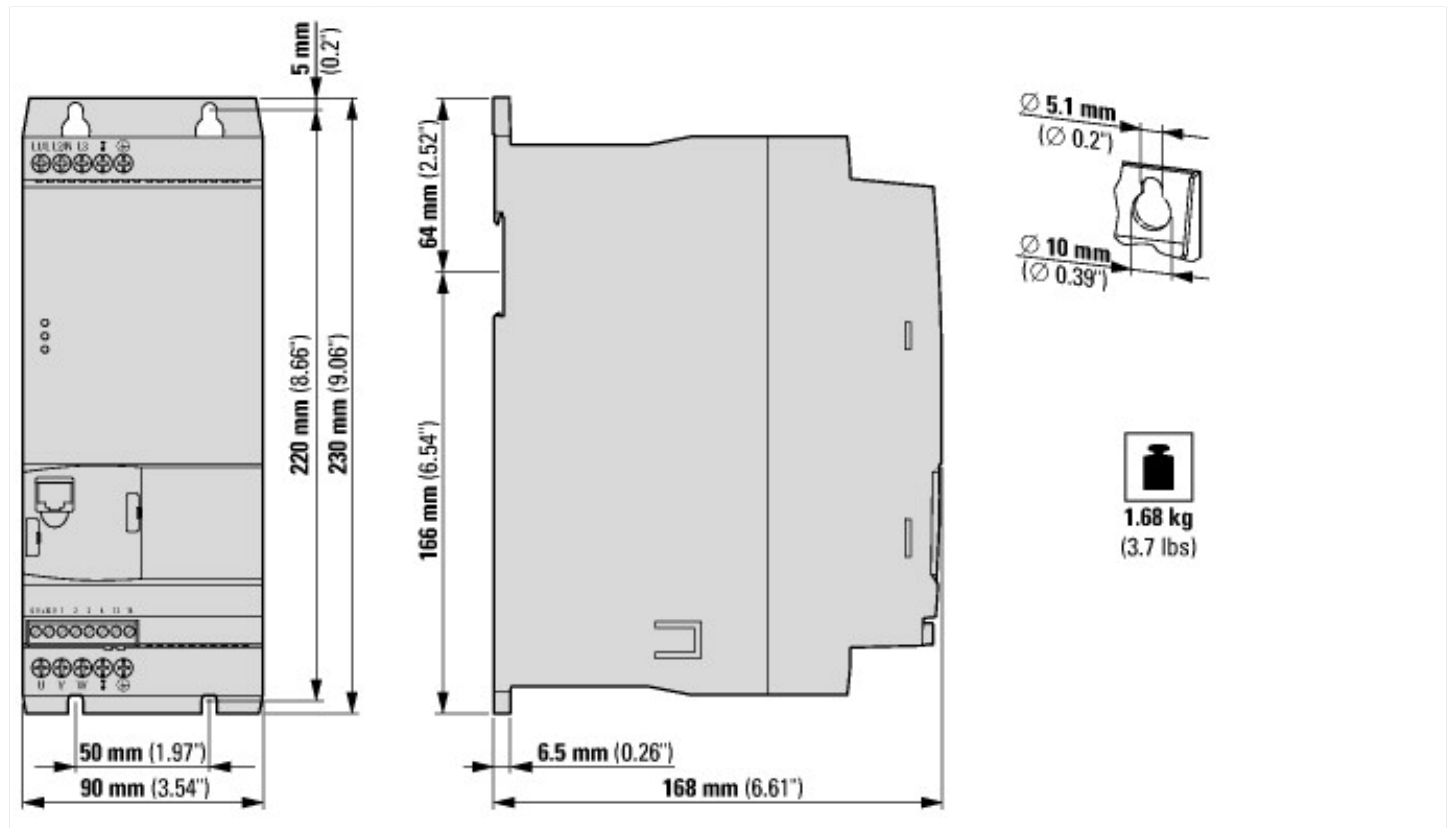
| | | | |
|--|----|--|-----------|
| Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857) | | | |
| Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) | | | |
| Mains voltage | V | | 380 - 480 |
| Mains frequency | | | 50/60 Hz |
| Number of phases input | | | 3 |
| Number of phases output | | | 3 |
| Max. output frequency | Hz | | 500 |
| Max. output voltage | V | | 500 |
| Nominal output current I _{2N} | A | | 11.3 |
| Max. output at quadratic load at rated output voltage | kW | | 5.5 |
| Max. output at linear load at rated output voltage | kW | | 5.5 |
| Relative symmetric net frequency tolerance | % | | 10 |
| Relative symmetric net voltage tolerance | % | | 10 |
| Number of analogue outputs | | | 0 |
| Number of analogue inputs | | | 1 |
| Number of digital outputs | | | 0 |
| Number of digital inputs | | | 4 |
| With control element | | | No |
| Application in industrial area permitted | | | Yes |
| Application in domestic- and commercial area permitted | | | Yes |
| Supporting protocol for TCP/IP | | | No |
| Supporting protocol for PROFIBUS | | | No |
| Supporting protocol for CAN | | | No |
| Supporting protocol for INTERBUS | | | No |
| Supporting protocol for ASI | | | No |
| Supporting protocol for KNX | | | No |
| Supporting protocol for Modbus | | | Yes |
| Supporting protocol for Data-Highway | | | No |
| Supporting protocol for DeviceNet | | | No |
| Supporting protocol for SUCONET | | | No |
| Supporting protocol for LON | | | No |
| Supporting protocol for PROFINET IO | | | No |
| Supporting protocol for PROFINET CBA | | | No |
| Supporting protocol for SERCOS | | | No |
| Supporting protocol for Foundation Fieldbus | | | No |
| Supporting protocol for EtherNet/IP | | | Yes |
| Supporting protocol for AS-Interface Safety at Work | | | No |

| | | |
|---|----|-------------|
| Supporting protocol for DeviceNet Safety | | No |
| Supporting protocol for INTERBUS-Safety | | No |
| Supporting protocol for PROFIsafe | | No |
| Supporting protocol for SafetyBUS p | | No |
| Supporting protocol for BACnet | | No |
| Supporting protocol for other bus systems | | Yes |
| Number of HW-interfaces industrial Ethernet | | 0 |
| Number of interfaces PROFINET | | 0 |
| Number of HW-interfaces RS-232 | | 0 |
| Number of HW-interfaces RS-422 | | 0 |
| Number of HW-interfaces RS-485 | | 1 |
| Number of HW-interfaces serial TTY | | 0 |
| Number of HW-interfaces USB | | 0 |
| Number of HW-interfaces parallel | | 0 |
| Number of HW-interfaces other | | 0 |
| With optical interface | | No |
| With PC connection | | Yes |
| Integrated breaking resistance | | No |
| 4-quadrant operation possible | | No |
| Type of converter | | U converter |
| Degree of protection (IP) | | IP20 |
| Degree of protection (NEMA) | | Other |
| Height | mm | 230 |
| Width | mm | 90 |
| Depth | mm | 169 |

Approvals

| | | |
|--------------------------------------|--|---|
| Product Standards | | UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No. | | E172143 |
| UL Category Control No. | | NMMS, NMMS7 |
| CSA File No. | | UL report applies to both US and Canada |
| North America Certification | | UL listed, certified by UL for use in Canada |
| Specially designed for North America | | No |
| Suitable for | | Branch circuits |
| Max. Voltage Rating | | 3- 480 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey) |
| Degree of Protection | | IEC: IP20 |

Dimensions



Additional product information (links)

CA04020001Z-EN Product Range Catalog: Efficient Engineering for Starting and Controlling Motors

http://www.eaton.eu/DE/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct_1095238.pdf